# <span id="page-0-0"></span>Verifying Unsolvability in Classical Planning with VeriPB

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<span id="page-1-0"></span>Planning Task  $\Pi = \langle V, I, A, \gamma \rangle$ 

- $\bullet$  state variables  $V$
- $\bullet$  initial state  $I$
- actions A
- goal  $\gamma$

Planning Task  $\Pi = \langle V, I, A, \gamma \rangle$ 

- state variables  $V = \{money, cake, eaten\}$
- $\bullet$  initial state  $I$
- actions A
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A = \{buy, sell, eat\}
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• goal  $\gamma$ 

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- state variables  $V = \{money, cake, eaten\}$
- initial state  $I = \{money, cake, eaten\}$

\n- actions 
$$
A = \{buy, sell, eat\}
$$
\n

• goal  $\gamma = \{ cake, eaten\}$ 

#### <span id="page-6-0"></span>Each action has a precondition, add effect, delete effect



<span id="page-7-0"></span>Task induces a directed graph called state space

#### <span id="page-8-0"></span>Task induces a directed graph called state space



<span id="page-9-0"></span>Use a planner to find a sequence that leads from the initial state to the goal. MyPlanner 1.0:

•  $[buy, eat, buy]$ 

Don't trust it? Verify it by executing the plan.

<span id="page-10-0"></span>Plan: [buy, eat, buy]



<span id="page-11-0"></span>Use another planner to find a sequence that leads from the initial state to the goal. MyPlanner 2.0:

• unsolvable

How to verify? With a Certificate.

<span id="page-12-0"></span>unsolvable?



<span id="page-13-0"></span>



# <span id="page-14-0"></span>Inductive Set

#### Inductive Set

If state s is a member of inductive set  $\varphi$ , then all successors of s are members of  $\varphi$ , too.

Idea based on Salomé Eriksson Certifying Planning Systems: Witnesses for Unsolvability (2019)

<span id="page-15-0"></span>

- Find a set  $\varphi$  (with compact representation) and prove that
	- $\varphi$  contains the initial state
	- $\varphi$  is an inductive set
	- $\varphi$  contains no goal state
- Such a set  $\varphi$  exists if and only if the task is unsolvable.

<span id="page-16-0"></span>

- Translate the planning task and  $\varphi$  into pseudo boolean constraints (PBCs)  $\sum a_i \cdot \ell_i \geq A$  with literals  $\ell_i$  and  $a_i, A \in \mathbb{N}$ .
- 2 ·  $\varphi$  + money + cake + eaten > 2
- $\overline{\varphi}$  +  $\overline{money}$  +  $\overline{calc}$  +  $\overline{eaten}$  > 2
- $4 \cdot \overline{b u v} + m \overline{o} n \overline{e v} + c \overline{a} k e' + \overline{m} \overline{o} n \overline{e v'} + e \overline{a} \overline{e} \overline{a} t e n} > 4$

<span id="page-17-0"></span>

- Use extended cutting plane proof system to deduce further constraints by
	- Addition of two PBCs.
	- Multiplication of a PBC.
	- Division of a PBC with rounding up.
	- Reification (introducing auxillary variables).

<span id="page-18-0"></span>

- We construct  $\varphi$  and the proof during the search.
	- For each search technique we have to come up with a fitting algorithm.
- This proof does not certify the planner.
- Only certifies this particular result.
- It can be checked by an independent party that knows nothing about planning.
	- For this we use VeriPB. $<sup>1</sup>$ </sup>

 $1B$ art Bogaerts, Stephan Gocht, Ciaran McCreesh, Jakob Nordström Certified Dominance and Symmetry Breaking for Combinatorial Optimisation. (JAIR 2023)

<span id="page-19-0"></span>

- Checks proof in the extended cutting plane proof system.
- The core checker (CakePB<sup>2</sup>) is verified by HOL4  $^3$ .

 $2B$ art Bogaerts, Ciaran McCreesh, Magnus O. Myreen, Jakob Nordström, Andy Oertel, and Yong Kiam Tan.

Documentation of VeriPB and CakePB for the SAT Competition 2023 (SAT Competition 2023)

 $3$ Norrish, M., Slind, K.: HOL-4 manuals (1998-2008), http://hol.sourceforge.net/



## <span id="page-20-0"></span>**Outlook**

- Next steps
	- Implement task to PBCs translation
	- Implement proof logging for naive search
- Future steps
	- Certify optimality if actions have cost
	- Argue with fancier algorithms
		- Abstractions, relaxations
		- Admissible heuristics

- <span id="page-21-0"></span>• (1) from framework:  $\overline{money} \geq 0$
- (2) from task:  $3 \cdot \overline{I} + money + \overline{calc} + \overline{eaten} \ge 3$
- (3) from  $\varphi$ :  $2 \cdot \varphi + money + cake + eaten \geq 2$

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- (2) from task:  $3 \cdot \overline{I} + money + \overline{calc} + \overline{eaten} \ge 3$
- (3) from  $\varphi$ :  $2 \cdot \varphi + money + cake + eaten \geq 2$
- (4) via (2)+(3):  $3 \cdot \overline{I} + 2 \cdot \varphi + 2 \cdot money + 1 + 1 > 5$
- (5) via (4)+2·(1):  $3 \cdot \overline{I} + 2 \cdot \varphi > 1$
- (6) via (5)/3:  $\lceil \frac{3}{3} \rceil$  $\frac{3}{3}$ ]  $\cdot \overline{I}$  +  $\lceil \frac{2}{3}$  $\frac{2}{3}$ ]  $\cdot \varphi \geq \lceil \frac{1}{3} \rceil$  $\overline{I} + \varphi > 1$

<span id="page-23-0"></span>In VeriPB this would look like:

- $\bullet$  1  $\text{"money} > = 0$ ;
- $3$   $\tilde{1}$  1 money 1  $\tilde{c}$  cake 1  $\tilde{c}$  eaten >= 3;
- 2 phi 1 money 1 cake 1 eaten >= 2;

<span id="page-24-0"></span>In VeriPB this would look like:

- $\bullet$  1  $\sim$  money >= 0;
- $3$   $\tilde{1}$  1 money 1  $\tilde{c}$  cake 1  $\tilde{c}$  eaten >= 3;
- 2 phi 1 money 1 cake 1 eaten  $>= 2$ ;
- pol 2 3 + 1 2 \* + 3 d
- e 1 <sup>~</sup>I 1 phi >= 1 ; -1

<span id="page-25-0"></span>• (1): 
$$
4 \cdot \overline{buy} + money + cake' + \overline{money'} + eq_{eaten} \ge 4
$$

• (2): 
$$
2 \cdot \overline{\varphi} + \overline{money} + \overline{cake} + \overline{eaten} \geq 2
$$

• (3): 
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\overline{eq_{eaten}} + eaten + \overline{eaten'} \ge 1
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• (4): 
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2 \cdot \varphi' + money' + cake' + eaten' \ge 2
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### [Appendix](#page-21-0)<br>
<u>OOOO</u>

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RUP with assumption  $\varphi + b u y + \overline{\varphi'} \geq 3$ 

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### <span id="page-37-0"></span>[Appendix](#page-21-0)<br>
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 via (3)

• 
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\varphi' \ge 1
$$
 via (4)

 $\overline{\varphi} + \overline{buy} + \varphi' \ge 1$ 

<span id="page-38-0"></span>Example subproof with RUP

#### In VeriPB this would look like

• rup 1  $\degree$ phi 1  $\degree$ buy 1 phi' >= 1;